An Introduction to Modal Logic I

Introduction and Historical remarks

Marco Cerami

Palacký University in Olomouc Department of Computer Science Olomouc, Czech Republic

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Modal Logic I

Introduction



Modal Logic

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What is Modal Logic?

"Ask three modal logician what modal logic is, and you are likely to get at least three different answers"

form the Preface of the book *Modal Logic* by P. Blackburn, M. de Rijke and I. Venema



Modal Logic I

What is a "modality"?

"A modality is an expression that, when applied to a sentence S, provides a new sentence about the mode in which S is true or about the mode in which it is accepted"

form the Introduction of the textbook *Lógica Modal* by R. Jansana and F. Bou



Modal Logic

Examples of modalities

- Aletic: necessary, possible, impossible;
- Deontic: obligatory, allowed, prohibited, legal, illegal;
- Doxastic: it is believed that;
- Epistemic: it is known that, everybody knows that;
- **Temporal**: always in the past, sometimes in the past, never in the past, always in the future, sometimes in the future, never in the future;
- Spatial: everywhere, somewhere, nowhere;
- Metalogic: valid, satisfiable, provable, consistent;
- Computational: in every state accessible from the present state, in some state accessible from the present state, in no state accessible from the present state;

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Two main notions of Modal Logic

- the logic of modal sentences and modal operators,
- the logic of relational structures (meant as Kripke frames).

the two notions **do not coincide**!!



Historical Remarks



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Modal Logic

The ancient era

- Period : IV century b.C. (Aristotelian school) and XII century a.C. (Scholastic).
- Systems: modal sentences.
- Modalities: aletic, epistemic.
 - Problem: derivation of modal sentences.
 - Method: Square of opposition.
- Strengths: definition (discovery) of the notion.
- Weaknesses: no axiomatic system,

no formal semantics in general,



The square of opposition



The syntactic era

The syntactic era

Period : 1918-1959.

Systems: axiomatic systems of modal logics.

Modalities: aletic, temporal.

Problem: proving system distinctness.

Method: Syntactic derivation.

algebraic methods are often used to prove system distinctness but not systematically (no completeness result).

Strengths: definition of systems and methods for further development.

Weaknesses: no formal semantics in general,

systems not systematically related to propositional or first order logic,

incomplete and undecidable systems. MESTMENTS IN

Lewis' systems

- The original motivation overcoming the unintuitive behavior of the classical material implication;
- to this end, Lewis in 1918 defines the strict implication;
- he defines five Hilbert-style system S1-S5;
- the notation includes just a conjunction \wedge and the strict implication —3;
- at the beginning there is **no semantics** defined;
- Lewis' systems are not defined as expansion of Classical Propositional Logic (CPL), rather as alternative intensional logics;
- Lewis' systems give a great impulse to the revival of Modal Logic.

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Lewis' systems S1

Axioms:

$$(A1) \quad (p \land q) \rightarrow (q \land p)$$

$$(A2) \quad (p \land q) \rightarrow p$$

$$(A3) \quad p \rightarrow (p \land p)$$

$$(A4) \quad ((p \land q) \land r) \rightarrow (p \land (q \land r))$$

$$(A5) \quad ((p \rightarrow q) \land (q \rightarrow r)) \rightarrow (p \rightarrow r)$$

$$(A6) \quad (p \land (p \rightarrow q)) \rightarrow q$$

Rules:

$$(US) \vdash_{S1} \varphi(p) \text{ implies } \vdash_{S1} \varphi(\psi)$$

$$(SSE) \vdash_{S1} \varphi(\chi) \text{ and } \vdash_{S1} \chi \equiv \psi \text{ imply } \vdash_{S1} \varphi(\psi)$$

$$(AD) \vdash_{S1} \varphi \text{ and } \vdash_{S1} \psi \text{ imply } \vdash_{S1} \varphi \land \psi$$

$$(SMP) \vdash_{S1} \varphi \text{ and } \vdash_{S1} \varphi \rightarrow \psi \text{ imply } \vdash_{S1} \psi$$

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Results

- Study of Lewis' systems from a syntactical point of view.
- Mainly results of **distinctness** between Lewis' systems.
- Gödel (1933) defines Lewis' systems using the modern notation, proves that Intuitionistic Propositional Logic (IPL) can be translated into S4.
- McKinsey and Tarski (1944-1948) define some kinds of algebraic semantics (*"algebras with operators"*) for Lewis' systems and show decidability for S2 and S4.



Beyond the syntactic era

- Carnap (1946) defines a semantics based on **state descriptions** (sets of formulas), an ancestor of Kripke frames.
- Jónsson and Tarski (1952) show how to represent algebras with operators as relational structures.
- Prior (1955) defines temporal logic and interprets it in (ω, <), a particular kind of Kripke frame.



The classical era

Period : 1959-1972.

- Systems: modal logics as semantically defined systems.
- Modalities: aletic, temporal, doxastic, deontic.
 - Problem: completeness, model theory.
 - Method: relational structures.
- Strengths: clear insight of several modal systems,

clear relations to propositional and first order logic.

Weaknesses: excessive trust on relational structures.



Kripke frames

- In 1959 Kripke publishes the paper A completeness theorem in Modal Logic;
- frames and models are defined and applied to prove completeness of modal axiomatic systems;
- Other authors (Hintikka, Kanger, Prior) previously worked with relational structures;
- Kripke presentation was the most clear and systematic;
- its application to Modal Logic is very natural;
- axiomatic systems of modal logics can be defined semantically from classes of frames (and vice-versa);
- authentic revolution in Modal Logic.

Results

- New questions, methods and perspective.
- Central notion of normal modal logics.
- Classification of modal logics through canonical models.
- Many completeness results.
- Firts results on finite model property.
- Lemmon and Scott (1966) **conjecture** that every modal system is frame complete.

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Beyond the classical era

- Lemmon (1966) systematically defines algebraic semantics (*"modal algebras"*) for modal logics.
- Thomason (1972) shows that there are **frame incomplete temporal logics**.
- Thomason and Prior (1974) show that there are **frame** incomplete modal logics.



The modern era

Period : 1972-present.

Systems: modal logics in a wide sense.

- Modalities: every kind of modality, introduction of the computational modalities.
 - Problem: algebraic completeness, model theory, expressivity, complexity.
 - Method: algebraic and relational structures, computational methods (automata, Turing machines).
 - Strengths: application of modal logics to other fields, in particular Theoretical Computer Science

Weaknesses: ?

Epistemic Algebras (Lemmon, 1966)

Definition

A structure $\mathbf{A} = \langle A, \cap, -, P, 0, 1 \rangle$ of type $\langle 2, 1, 1, 0, 0 \rangle$ is said to be an *Epistemic Algebra* iff

We denote by EA the class of Epistemic Algebras.

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Results

- Frame incompleteness results (Thomason, Prior, 1974).
- Revival of **algebraic semantics** (Lemmon, 1966; Goldblatt, Thomason, 1974).
- Definition of **Propositional Dynamic Logic** as the logic of computer programs (Pratt, 1976).
- Study of the **computational properties** of several modal logics (Ladner, 1977).
- The study of the **expressive capabilities** of modal logics (Gabbay, 1983).
- **Application** to Knowledge Representation (Schild, 1990) and many other areas of Computer Science.

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Propositional Dynamic Logic (Pratt, 1976)

- properties: φ, ψ, \dots (propositional formulas) atomic programs: π_1, π_2, \dots union of programs: \cup composition of programs: ; iteration of programs: * modality: $\langle \pi \rangle$
- The intended meaning of the formula $\langle \pi \rangle \varphi$ is:

"some terminating execution of program π leads to a state where property φ holds"

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