

Singular mixed boundary value problem

Irena Rachůnková

Department of Mathematics, Palacký University, Tomkova 40, 77900 Olomouc,
Czech Republic, e-mail: rachunko@inf.upol.cz

Abstract. We study singular boundary value problems with mixed boundary conditions of the form

$$u'' + f(t, u, u') = 0, \quad u'(0) = 0, \quad u(T) = 0,$$

where $[0, T] \subset \mathbb{R}$, $\mathcal{D} = (0, \infty) \times (-\infty, 0)$, f is a non-negative function and satisfies the Carathéodory conditions on $(0, T) \times \mathcal{D}$. Here, f can have a time singularity at $t = 0$ and/or $t = T$ and a space singularity at $x = 0$ and/or $y = 0$. We present conditions for the existence of solutions positive on $[0, T)$ and having continuous first derivatives on $[0, T]$.

Keywords. Singular mixed boundary value problem, positive solution, lower and upper functions, convergence of approximate regular problems

Mathematics Subject Classification 2000. 34B16, 34B18

1 Introduction

We investigate the solvability of the singular mixed boundary value problem

$$u'' + f(t, u, u') = 0, \quad u'(0) = 0, \quad u(T) = 0, \quad (1.1)$$

where $[0, T] \subset \mathbb{R}$, $\mathcal{D} = (0, \infty) \times (-\infty, 0)$, f satisfies the Carathéodory conditions on $(0, T) \times \mathcal{D}$. Here, f can have a time singularity at $t = 0$ and/or at $t = T$ and a space singularity at $x = 0$ and/or at $y = 0$. We prove the existence of solutions of (1.1) which are positive on $[0, T)$ and have continuous first derivatives on $[0, T]$.

Let $[a, b] \subset \mathbb{R}$, $\mathcal{M} \subset \mathbb{R}^2$. Recall that a real valued function f satisfies the Carathéodory conditions on the set $[a, b] \times \mathcal{M}$ if

- (i) $f(\cdot, x, y) : [a, b] \rightarrow \mathbb{R}$ is measurable for all $(x, y) \in \mathcal{M}$,

(ii) $f(t, \cdot, \cdot) : \mathcal{M} \rightarrow \mathbb{R}$ is continuous for a.e. $t \in [a, b]$,
 (iii) for each compact set $K \subset \mathcal{M}$ there is a function $m_K \in L_1[0, T]$ such that $|f(t, x, y)| \leq m_K(t)$ for a.e. $t \in [a, b]$ and all $(x, y) \in K$.
 We write $f \in \text{Car}([a, b] \times \mathcal{M})$. By $f \in \text{Car}((0, T) \times \mathcal{D})$ we mean that $f \in \text{Car}([a, b] \times \mathcal{D})$ for each $[a, b] \subset (0, T)$ and $f \notin \text{Car}([0, T] \times \mathcal{D})$.

Definition 1.1. Let $f \in \text{Car}((0, T) \times \mathcal{D})$.

We say that f has a *time singularity* at $t = 0$ and/or at $t = T$ if there exists $(x, y) \in \mathcal{D}$ such that

$$\int_0^\varepsilon |f(t, x, y)| dt = \infty \quad \text{and/or} \quad \int_{T-\varepsilon}^T |f(t, x, y)| dt = \infty$$

for each sufficiently small $\varepsilon > 0$. The point $t = 0$ and/or $t = T$ will be called a *singular point of f* .

We say that f has a *space singularity* at $x = 0$ and/or at $y = 0$ if

$$\limsup_{x \rightarrow 0^+} |f(t, x, y)| = \infty \quad \text{for a.e. } t \in [0, T] \text{ and for some } y \in (-\infty, 0)$$

and/or

$$\limsup_{y \rightarrow 0^-} |f(t, x, y)| = \infty \quad \text{for a.e. } t \in [0, T] \text{ and for some } x \in (0, \infty).$$

The importance of singular mixed problems is derived, in part, from the fact that they arised when searching for positive, radially symmetric solutions to the nonlinear elliptic partial differential equations

$$\Delta u + g(r, u) = 0 \text{ on } \Omega, \quad u|_\Gamma = 0, \quad (1.2)$$

where Ω is the open unit disk in \mathbb{R}^n (centered at the origin), Γ is its boundary, and r is the radial distance from the origin. Radially symmetric solutions to this problem are solutions of the following ordinary differential equation with the mixed boundary conditions (see e.g. [9] or [11])

$$u'' + \frac{n-1}{t}u' + g(t, u) = 0, \quad u'(0) = 0, \quad u(1) = 0, \quad (1.3)$$

where $f(t, x, y) = \frac{n-1}{t}y + g(t, x)$ has a time singularity at $t = 0$.

Particularly, Gatica, Olikier and Waltman [10] investigated problem (1.3) with $g(t, x) = \psi(t)x^{-\alpha}$, $\alpha \in (0, 1)$, $\psi \in C[0, 1)$. Since $\alpha > 0$, we see that g has a space singularity at $x = 0$. In [10], moreover, ψ is allowed to have a time singularity at $t = 1$ and the authors have found conditions for the existence of a solution positive on $[0, 1)$.

In the mathematical literature there are two approaches to solvability of singular problems which depend on different definitions of a solution. Here, we work with the following one:

Definition 1.2. By a *solution* of problem (1.1) we understand a function $u \in AC^1[0, T]$ satisfying

$$u''(t) + f(t, u(t), u'(t)) = 0 \quad \text{for a.e. } t \in [0, T], \quad u'(0) = u(T) = 0. \quad (1.4)$$

We see that our solution has continuous first derivatives on $[0, T]$, particularly at the singular point $t = T$. Note that such solution of (1.3) is important for the associated problem (1.2). The alternative approach is based on the following definition of a "solution", which we will call a w-solution.

Definition 1.3. By a *w-solution* of problem (1.1) we understand a function $u \in AC_{loc}^1[0, T]$ satisfying (1.4).

Hence having a w-solution we do not know a behaviour of its derivative near the singular point $t = T$. For the existence of w-solutions of (1.1) we refer to [1] - [3], [6], [14] - [16], while the existence of solutions of (1.1) can be found e.g. in [4], [5], [7], [8], [12], [13], [17], [18]. Note that the papers [2], [4], [13], [17], [18] deal with problem (1.1) allowing just space singularities but not time ones and the papers [5], [7], [8] consider both time and space (at $x = 0$) singularities. Motivated by the existence results in [2] and [5] which are based on a lot of rather complicated conditions, we offer simple conditions which guarantee the existence of solutions for (1.1) provided both time and space (at $x = 0$ and moreover at $y = 0$) are allowed.

2 Lower and upper functions

In the investigation of singular problems lower and upper functions of corresponding regular problems can be a fruitful tool. See [5], [12] or [15]. Therefore we first consider an auxiliary regular mixed problem

$$u'' + h(t, u, u') = 0, \quad u'(0) = 0, \quad u(T) = 0, \quad (2.1)$$

where $h \in Car([0, T] \times \mathbb{R}^2)$.

Definition 2.1. A function $\sigma \in C[0, T]$ is called a *lower function* of (2.1) if there exists a finite set $\Sigma \subset (0, T)$ such that $\sigma \in AC_{loc}^1([0, T] \setminus \Sigma)$, $\sigma'(\tau+), \sigma'(\tau-) \in \mathbb{R}$ for each $\tau \in \Sigma$,

$$\sigma''(t) + h(t, \sigma(t), \sigma'(t)) \geq 0 \quad \text{for a.e. } t \in [0, T] \quad (2.2)$$

and

$$\sigma'(0) \geq 0, \quad \sigma(T) \leq 0, \quad \sigma'(\tau-) < \sigma'(\tau+) \quad \text{for each } \tau \in \Sigma. \quad (2.3)$$

If the inequalities in (2.2) and (2.3) are reversed, then σ is called *an upper function* of (2.1).

In what follows we will need the classical lower and upper functions result for regular mixed problem (2.1):

Lemma 2.2. [15], Lemma 3.7. *Let σ_1 and σ_2 be lower and upper functions for problem (2.1) such that $\sigma_1 \leq \sigma_2$ on $[0, T]$. Assume also that there is a function $\psi \in L_1[0, T]$ such that*

$$|h(t, x, y)| \leq \psi(t) \quad \text{for a.e. } t \in [0, T], \quad \text{all } x \in [\sigma_1(t), \sigma_2(t)], \quad y \in \mathbb{R}. \quad (2.4)$$

Then problem (2.1) has a solution $u \in AC^1[0, T]$ satisfying

$$\sigma_1(t) \leq u(t) \leq \sigma_2(t) \quad \text{for } t \in [0, T]. \quad (2.5)$$

3 Main result and example

Theorem 3.1. *Let $f \in Car((0, T) \times \mathcal{D})$ can have time singularities at $t = 0, t = T$ and space singularities at $x = 0, y = 0$. Assume that there exist $\varepsilon \in (0, 1)$, $\nu \in (0, T)$, $c \in (\nu, \infty)$ such that*

$$f(t, c(T-t), -c) = 0 \quad \text{for a.e. } t \in [0, T], \quad (3.1)$$

$$0 \leq f(t, x, y) \quad \text{for a.e. } t \in [0, T], \quad \text{all } x \in (0, c(T-t)], y \in [-c, 0), \quad (3.2)$$

$$\varepsilon \leq f(t, x, y) \quad \text{for a.e. } t \in [0, \nu], \quad \text{all } x \in (0, c(T-t)], y \in [-\nu, 0). \quad (3.3)$$

Then problem (1.1) has a solution $u \in AC^1[0, T]$ satisfying

$$0 < u(t) < c(T-t), \quad -c < u'(t) < 0 \quad \text{for } t \in (0, T). \quad (3.4)$$

PROOF. Let $k \in \mathbb{N}$, $k \geq 3/T$.

Step 1. Approximate solutions. For $t \in [1/k, T - 1/k]$, $x \in \mathbb{R}$ put

$$\alpha_k(t, x) = \begin{cases} c(T-t) & \text{if } x > c(T-t) \\ x & \text{if } c/k \leq x \leq c(T-t) \\ c/k & \text{if } x < c/k \end{cases},$$

and for $y \in \mathbb{R}$ denote

$$\beta_k(y) = \begin{cases} -\varepsilon/k & \text{if } y > -\varepsilon/k \\ y & \text{if } -c \leq y \leq -\varepsilon/k \\ -c & \text{if } y < -c \end{cases},$$

$$\gamma(y) = \begin{cases} \varepsilon & \text{if } y \geq -\nu \\ \varepsilon(c+y)/(c-\nu) & \text{if } -c < y < -\nu \\ 0 & \text{if } y \leq -c \end{cases} .$$

For a.e. $t \in [0, T]$ and $x, y \in \mathbb{R}$ define

$$f_k(t, x, y) = \begin{cases} \gamma(y) & \text{if } t \in [0, 1/k) \\ f(t, \alpha_k(t, x), \beta_k(y)) & \text{if } t \in [1/k, T - 1/k] \\ 0 & \text{if } t \in (T - 1/k, T] \end{cases} .$$

Then $f_k \in Car([0, T] \times \mathbb{R}^2)$ and there is $\psi_k \in L_1[0, T]$ such that

$$|f_k(t, x, y)| \leq \psi_k(t) \quad \text{for a.e. } t \in [0, T], \text{ all } x, y \in \mathbb{R}. \quad (3.5)$$

We have got an auxiliary regular problem

$$u'' + f_k(t, u, u') = 0, \quad u'(0) = 0, \quad u(T) = 0. \quad (3.6)$$

Conditions (3.2) and (3.1) yield

$$f_k(t, 0, 0) \geq 0, \quad f_k(t, c(T-t), -c) = 0 \quad \text{for a.e. } t \in [0, T].$$

Put $\sigma_1(t) = 0$, $\sigma_2(t) = c(T-t)$ on $[0, T]$. Then σ_1 and σ_2 are lower and upper functions of (3.6). Hence, by Lemma 2.2, problem (3.6) has a solution u_k and

$$0 \leq u_k(t) \leq c(T-t) \quad \text{on } [0, T]. \quad (3.7)$$

Step 2. A priori estimates of approximate solutions. Since $u'_k(0) = 0$ and $f_k(t, x, y) \geq 0$ for a.e. $t \in [0, T]$ and all $x, y \in \mathbb{R}$, we get $u'_k(t) \leq 0$ on $[0, T]$. Condition (3.7) and $u_k(T) = 0$ give $u_k(T) - u_k(t) \geq -c(T-t)$ which yields $u'_k(T) \geq -c$. Since u'_k is non-increasing on $[0, T]$, we have proved

$$-c \leq u'_k(t) \leq 0 \quad \text{on } [0, T]. \quad (3.8)$$

Due to $u'_k(0) = 0$, there is $t_k \in (0, T]$ such that

$$-\nu \leq u'_k(t) \leq 0 \quad \text{for } t \in [0, t_k].$$

If $t_k \geq \nu$, we get by (3.3)

$$u'_k(t) \leq -\varepsilon t \quad \text{for } t \in [0, \nu]. \quad (3.9)$$

Assume that $t_k < \nu$ and $u'_k(t) < -\nu$ for $t \in (t_k, \nu]$. Then

$$u'_k(t) \leq -\varepsilon t \quad \text{for } t \in [0, t_k].$$

Since $-\nu < -\varepsilon t$ for $t \in (t_k, \nu]$, we get (3.9) again. Integrating (3.9) on $[0, \nu]$ and using the concavity of u_k on $[0, T]$ we deduce that

$$\frac{\varepsilon \nu^2}{2T}(T-t) \leq u_k(t) \quad \text{on } [0, T]. \quad (3.10)$$

Step 3. Convergence of a sequence of approximate solutions. Consider the sequence $\{u_k\}$. Choose an arbitrary compact interval $J \subset (0, T)$. By virtue of (3.7)-(3.10) there is $k_0 \in \mathbb{N}$ such that for each $k \in \mathbb{N}$, $k \geq k_0$

$$\frac{c}{k_0} \leq u_k(t) \leq c(T-t), \quad -c \leq u'_k(t) \leq -\frac{\varepsilon}{k_0} \quad \text{on } J, \quad (3.11)$$

and hence there is $\psi \in L_1(J)$ such that

$$|f_k(t, u_k(t), u'_k(t))| \leq \psi(t) \quad \text{a.e. on } J. \quad (3.12)$$

Using conditions (3.7), (3.8), (3.12), the Arzelà-Ascoli theorem and the diagonalization principle, we can choose $u \in C[0, T] \cap C^1(0, T)$ and a subsequence of $\{u_k\}$ which we denote for the simplicity in the same way such that

$$\begin{aligned} \lim_{k \rightarrow \infty} u_k &= u \quad \text{uniformly on } [0, T], \\ \lim_{k \rightarrow \infty} u'_k &= u' \quad \text{locally uniformly on } (0, T). \end{aligned} \quad (3.13)$$

Therefore we have $u(T) = 0$.

Step 4. Convergence of a sequence of approximate problems. Choose an arbitrary $\xi \in (0, T)$ such that

$$f(\xi, \cdot, \cdot) \quad \text{is continuous on } (0, \infty) \times (-\infty, 0).$$

By (3.11) there exist a compact interval $J^* \subset (0, T)$ and $k_* \in \mathbb{N}$ such that $\xi \in J^*$ and for each $k \geq k_*$

$$u_k(\xi) > \frac{c}{k_*}, \quad u'_k(\xi) < -\frac{\varepsilon}{k_*}, \quad J^* \subset [1/k, T - 1/k].$$

Therefore

$$f_k(\xi, u_k(\xi), u'_k(\xi)) = f(\xi, u_k(\xi), u'_k(\xi))$$

and, due to (3.13),

$$\lim_{k \rightarrow \infty} f_k(t, u_k(t), u'_k(t)) = f(t, u(t), u'(t)) \quad \text{for a.e. } t \in (0, T). \quad (3.14)$$

Choose an arbitrary $t \in (0, T)$. Then there exists a compact interval $J \subset (0, T)$ such that (3.12) holds for all sufficiently large k . By virtue of (3.6) we get

$$u'_k(T/2) - u'_k(t) = \int_{T/2}^t f_k(s, u_k(s), u'_k(s)) ds.$$

Letting $k \rightarrow \infty$ and using (3.12), (3.13), (3.14) and the Lebesgue convergence theorem on J , we get

$$u'(T/2) - u'(t) = \int_{T/2}^t f(s, u(s), u'(s)) ds \quad \text{for each } t \in (0, T). \quad (3.15)$$

Therefore $u \in AC_{loc}^1(0, T)$ satisfies

$$u''(t) + f(t, u(t), u'(t)) = 0 \quad \text{a.e. on } (0, T). \quad (3.16)$$

Further, according to (3.6) and (3.8) we have for each $k \geq 3/T$

$$\int_0^T f_k(s, u_k(s), u'_k(s)) ds = -u'_k(T) \leq c,$$

which together with (3.2), (3.7), (3.8) and (3.14) yield, by the Fatou lemma, that $f(t, u(t), u'(t)) \in L_1[0, T]$. Therefore, by (3.16), $u \in AC^1[0, T]$. Moreover for each $k \geq 3/T$ and $t \in (0, T)$

$$|u'_k(t)| \leq \int_0^t |f_k(s, u_k(s), u'_k(s)) - f(s, u(s), u'(s))| ds + \int_0^t |f(s, u(s), u'(s))| ds.$$

Hence, by (3.13) and (3.14), for each $\varepsilon > 0$ there exists $\delta > 0$ and for each $t \in (0, \delta)$ there exists $k_0 = k_0(\varepsilon, t) \in \mathbb{N}$ such that

$$|u'(t)| \leq |u'(t) - u'_{k_0}(t)| + |u'_{k_0}(t)| < \varepsilon.$$

It means that $u'(0) = \lim_{t \rightarrow 0^+} u'(t) = 0$. We have proved that u is a solution of problem (1.1).

Example. Let $\alpha, \gamma \in (0, \infty)$, $k, \beta \in [0, \infty)$. By Theorem 3.1 problem

$$u'' + (u^{-\alpha} + u^\beta + k(-u')^{-\gamma} + 1)(1 + (u')^3) = 0, \quad u'(0) = 0, \quad u(1) = 0 \quad (3.17)$$

has a solution $u \in AC^1[0, 1]$ satisfying

$$0 < u(t) < 1 - t, \quad -1 < u'(t) < 0 \quad \text{for } t \in (0, 1). \quad (3.18)$$

Note that Theorem 2.2 in [2] yields the existence of a solution of problem (3.17) positive on $[0, 1)$ provided the nonlinearity $f(t, x, y) = (x^{-\alpha} + x^\beta + 1)(1 + y^3)$ has a weak space singularity (i.e. $\alpha \in (0, 1)$) at $x = 0$ and no singularity (i.e. $k = 0$) at y . On the other hand, due to Theorem 3.1, we get a solution u of problem (3.17) satisfying (3.18) even for $f(t, x, y) = (x^{-\alpha} + x^\beta + k(-y)^{-\gamma} + 1)(1 + y^3)$ having a strong space singularity ($\alpha \geq 1$) at $x = 0$ and moreover a space singularity ($k > 0$) at $y = 0$.

Acknowledgments

Supported by the grant No. 201/04/1077 of the Grant Agency of the Czech Republic and by the Council of Czech Government MSM 6198959214

References

- [1] R. P. AGARWAL, D. O'REGAN. Singular boundary value problems for superlinear second order ordinary and delay differential equations. *J. Differential Equations* **130** (1996), 333–355.
- [2] R. P. AGARWAL, D. O'REGAN. Nonlinear superlinear singular and nonsingular second order boundary value problems. *J. Differential Equations* **143** (1998), 60–95.
- [3] R. P. AGARWAL, D. O'REGAN. Singular problems motivated from classical upper and lower solutions. *Acta Math. Hungar.* **100** (3) (2003), 245–256.
- [4] R. P. AGARWAL, D. O'REGAN, S. STANĚK. Existence of positive solutions for boundary-value problems with singularities in phase variables. *PROC. EDINB. MATH. SOC.* **47** (2004), 1–13.
- [5] R. P. AGARWAL, S. STANĚK. Nonnegative solutions of singular boundary value problems with sign changing nonlinearities. *Comp. Math. Appl.* **46** (2003), 1827–1837.
- [6] J. V. BAXLEY. Some singular nonlinear boundary value problems. *SIAM J. Math. Anal.* **22** (1991), 463–479.
- [7] J. V. BAXLEY, G. S. GERSDORFF. Singular reaction-diffusion boundary value problem. *J. Differential Equations* **115** (1995), 441–457.
- [8] J. V. BAXLEY, K. P. SORRELLS. A class of singular nonlinear boundary value problems. *Math. Comp. Modelling* **32** (2000), 631–641.
- [9] H. BERESTYCKI, P. L. LIONS, L. A. PELETIER. An ODE approach to the existence of positive solutions for semilinear problems in \mathbb{R}^N . *Indiana Univ. Math. J.* **30** (1981), 141–157.
- [10] J. A. GATICA, V. OLIKER AND P. WALTMAN. Singular nonlinear boundary value problems for second-order ordinary differential equations. *J. Differential Equations* **79** (1989), 62–78.
- [11] B. GIDAS, W. M. NI, L. NIRENBERG. Symmetry of positive solutions of nonlinear elliptic equations in \mathbb{R}^N . *Adv. Math. Suppl. Studies* **7A** (1981), 369–402.
- [12] R. KANNAN AND D. O'REGAN. Singular and nonsingular boundary value problems with sign changing nonlinearities. *J. Inequal. Appl.* **5** (2000), 621–637.

- [13] P. KELEVEDJIEV. Nonnegative solutions to some second-order boundary value problems. *Nonlinear Analysis* **36** (1999), 481–494.
- [14] I. T. KIGURADZE. On some singular boundary value problems for ordinary differential equations. *Tbilis. Univ. Press*, Tbilisi 1975 (in Russian).
- [15] I.T. KIGURADZE AND B.L. SHEKHTER. Singular boundary value problems for second order ordinary differential equations. *Itogi Nauki Tekh., Ser. Sovrm. Probl. Mat., Viniti* **30** (1987), 105–201 (in Russian).
- [16] D. O'REGAN. Theory of singular boundary value problems. *World Scientific*, Singapore 1994.
- [17] J. Y. SHIN. A singular nonlinear differential equation arising in the Homann flow. *J. Math. Anal. Appl.* **212** (1997), 443–451.
- [18] A. TINEO. On a class of singular boundary value problems which contains the boundary conditions $x'(0) = x(1) = 0$. *J. Differential Equations* **113** (1994), 1–16.